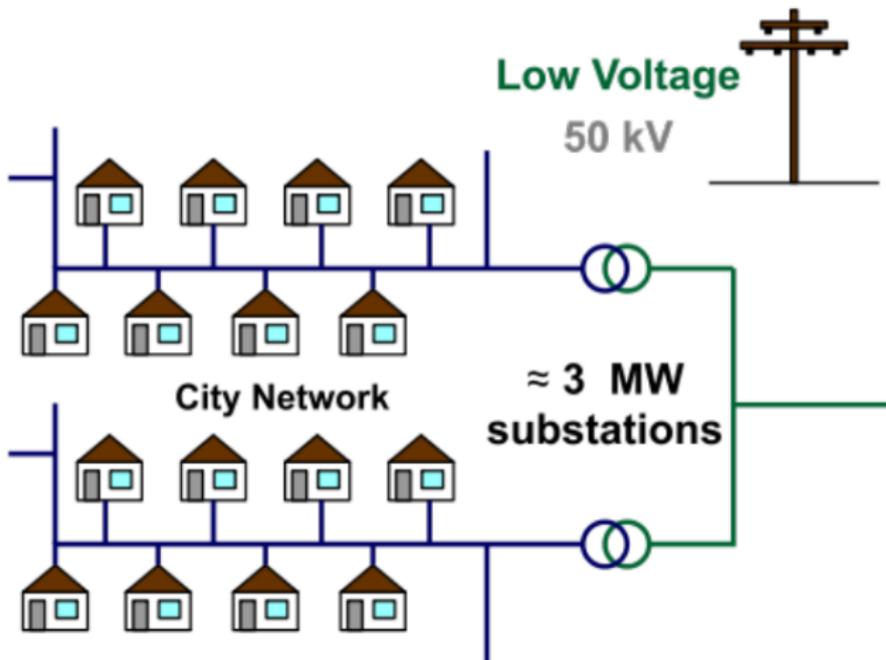


Electric Distribution Network: Substations and Houses



Autonomous Demand Response

- Distribution System Operators (DSOs) compute price tariffs for residential users
- Expected Power Profiles (EPPs): how residential users will respond to price tariffs
- DSOs compute price tariffs so that EPPs do not threaten substations safety
 - in each t , Aggregated Power Demand (APD) must be below the substation safety power threshold (e.g., 400 kW)

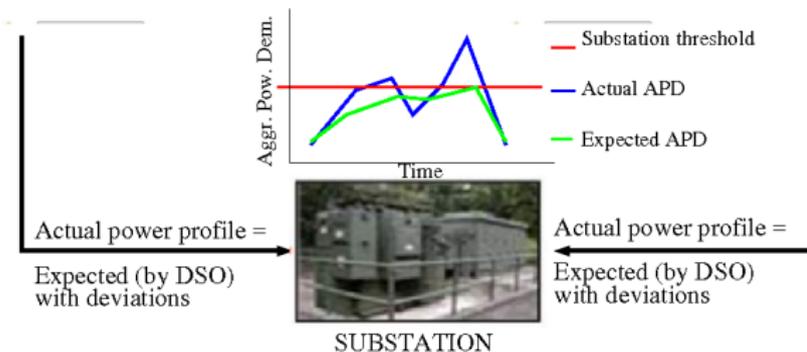
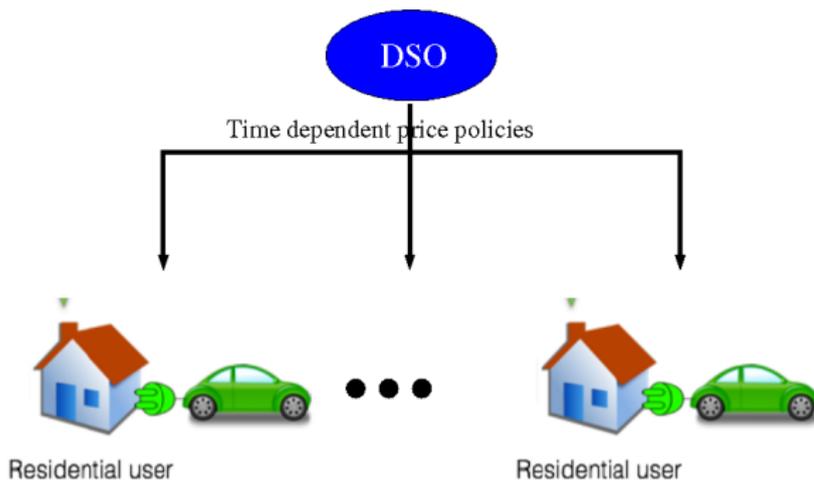
Autonomous Demand Response

- Residential users may or may not follow their corresponding EPPs
 - there may be automatic tools to enforce EPPs
 - implemented on small devices on users premises
 - still, there is no guarantee, due to unexpected needs, bad forecasts, limited computational resources, etc.

Problem

Given that users may deviate from EPPs with a given probability distribution, what is the resulting probability distribution for the APD?

Problem at a Glance

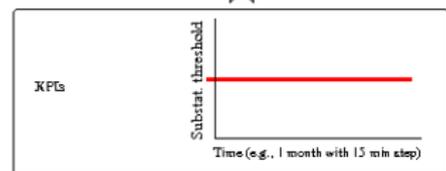
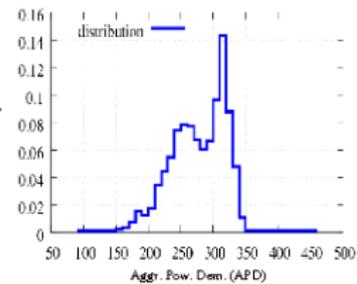
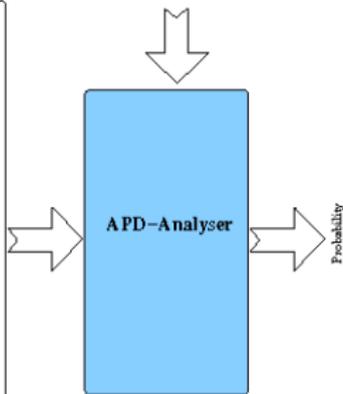
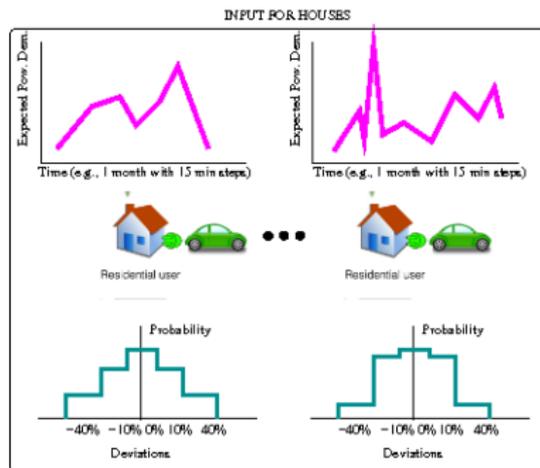


APD-Analyser

- We present the APD-Analyser tool
- Main goal: compute the probability distribution for the APD
- So as to compute KPIs on it
 - probability distribution that a given substation threshold is exceeded
 - rank APD probability distributions according to their similarity to desired shapes

APD-Analyzer: Input and Output

$0 < \epsilon < 1$: tolerance
 $0 < \delta < 1$: numerical accuracy
 $\tau \in \mathbb{N}^+$: discretisation for APD



APD-Analyser: Input

- Set of residential users U connected to the same substation
- Period of time T (e.g., one month), divided in time-slots (e.g., 15 minutes)
- Expected Power Profiles (EPP)
 - one for each user $u \in U$: for each time-slot $t \in T$, the expected power demand of u in t
 - $p_u : T \rightarrow \mathbb{R}$
 - if $p_u(t) < 0$, production from PV panels exceeds consumption in time-slot t
- A probabilistic model for users deviations from EPPs
 - a real function $dev_u : D_u \rightarrow [0, 1]$, for each user $u \in U$
 - $\int_{D_u} dev_u(x) dx = 1$
 - $\int_a^b dev_u(x) dx =$ probability that actual power demand of u in any time-slot $t \in T$ is in $[(1+a)p_u(t), (1+b)p_u(t)]$

APD-Analyser: Input

- Substation safety requirements
 - $p_s : T \rightarrow \mathbb{R}$
 - for each $t \in T$, DSO wants the APD to be below $p_s(t)$
 - that is, $\forall t \in T \rightarrow \sum_{u \in U} p_u(t) \leq p_s(t)$
- Key Performance Indicators (KPIs)
 - e.g., probability distribution that $p_s(t)$ is exceeded in any $t \in T$
- Parameters
 - $0 < \delta, \varepsilon < 1$: as for output probability distributions, the values must be correct up to tolerance ε with statistical confidence δ
 - $\Pr[(1 - \varepsilon)\mu \leq \tilde{\mu} \leq (1 + \varepsilon)\mu] \geq 1 - \delta$
 - μ : (unknown) correct value, $\tilde{\mu}$: computed value
 - $\gamma \in \mathbb{R}^+$: discretisation step for output probability distribution

APD-Analyser: Output

- Probability distribution for APD resulting from EPPs disturbed with given probabilistic disturbance model
 - easy to evaluate KPIs once such distribution is computed
 - formally: $\Psi(v, W)$ is the probability that APD takes a value in interval W in any time-slot t s.t. $p_s(t) = v$
- Exactly computing Ψ is infeasible, thus we compute $\tilde{\Psi}$ as a (ε, δ) approximation of a γ -discretisation of the APD
- For each γ -discretised value $w = \text{APD}_{\min} + k\gamma$, and for $v \in p_s(T)$, we compute $\tilde{\Psi}(v, w)$ s.t., with confidence at least $1 - \delta$:
 - if $\tilde{\Psi}(v, w) = \perp \notin [0, 1]$ then $\Psi(v, [w, w + \gamma)) < \varepsilon$
 - otherwise, $\Psi(v, [w, w + \gamma))$ is within $(1 \pm \varepsilon)\tilde{\Psi}(v, w)$

APD-Analyser: Algorithm

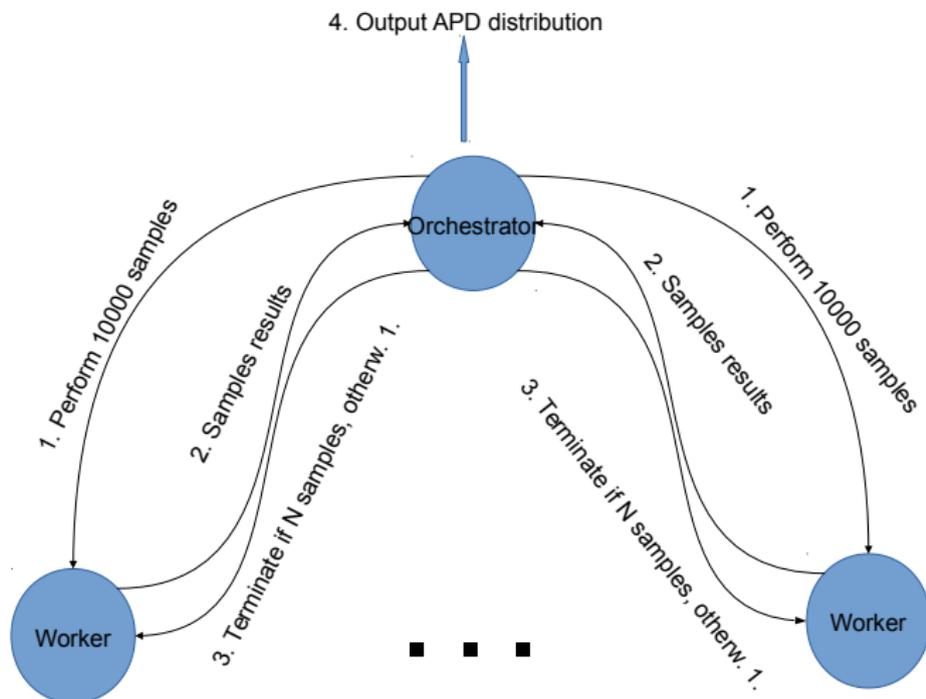
- *Monte-Carlo model checking*
 - goal: estimate the mean of a 0/1 random variable $Z_{v,w}$
 - taken at random a $t \in p_s^{-1}(v)$, is the value of the APD inside w , when perturbed using deviations model dev_u ?
- Method: perform N independent experiments (samples) for $Z_{v,w}$, and then the mean is $\frac{\sum_{i=1}^N Z_i}{N}$
 - Optimal Approximation Algorithm (OAA) by Dagum & al. (2000) + Quantitative Model Checking (QMC) by Grosu & Smolka (2005)
 - the value of N is automatically adjusted, at run-time, while performing the samples
 - so that the desired tolerance ε is achieved with desired accuracy δ

APD-Analyser: HPC Algorithm

- N can be prohibitively high
 - easily order of 10^9 in our experiments
 - if performed with a sequential algorithm, order of 1 month for the computation time
- We re-engineer the OAA to be run on a HPC infrastructure, i.e., a cluster
 - main obstacle: value of N depends on samples outcomes! To be computed at run-time
- One *orchestrator* node instructs *worker* nodes to perform given number of samples
 - worker nodes perform samples in parallel and send results to the orchestrator
 - the orchestrator is responsible for termination checking
 - that is: is current number of samples ok for desired ε, δ ?
- As a result, less than 2 hours of computation

APD-Analyser: HPC Implementation Sketch

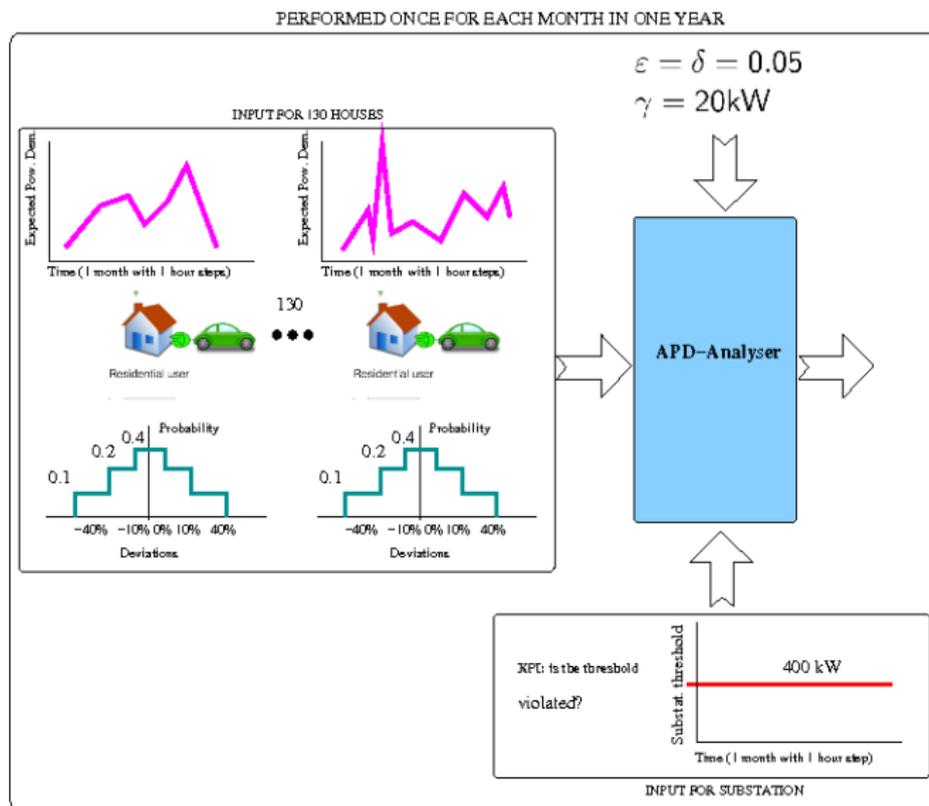
Steps 3-4: Monte-Carlo OAA (Dagum2000) and QMC (Grosu2005)



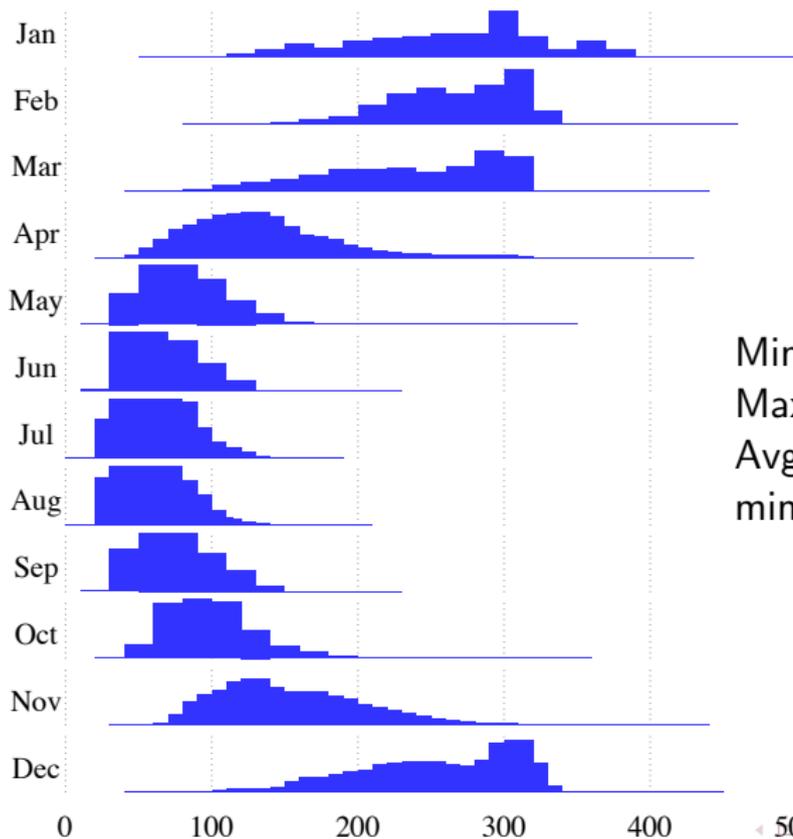
Experimental Evaluation: Case Study

- 130 houses in Denmark, all connected to the same substation
- EPPs computed by using methodologies from the literature
 - namely, computed as collaborative users which respond to individualised price policies
- Very liberal deviation model: up to $\pm 40\%$ variations with 10% probability, up to $\pm 20\%$ variations with 20% probability
- Challenging scenario: we want to compute the APD for each month of the year
 - by using time-slots of 1 day, we have $5^{30 \times 130}$ overall number of deviations

Experimental Evaluation: Case Study



Experimental Results



Min exec time: 4782 secs
Max exec time: 6448 secs
Avg exec time: 1 hour, 28
minutes and 7 seconds

Experimental Results: HPC Scalability

# workers	samples/sec	speedup	efficiency
1	5924.89	1×	100%
20	79275.028	13.38×	66.90%
40	162578.98	27.44×	68.60%
60	257791.96	43.51×	72.52%
80	335823.24	56.68×	70.85%

Conclusions

- We presented the HPC-based tool APD-Analyser
- Main purpose: support DSOs in analysing effects of price policies on aggregated power demand (APD) at substation level
 - especially for highly-fluctuating and individualised price policies
- From expected power profiles disturbed by probabilistic deviations (input) to probability distribution for APD (output)
- As a result, APD-Analyser enables safety assessment of price policies in highly dynamic ADR schemas

